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1 **New statistical methods for precipitation bias correction applied to WRF**
2 **model simulations in the Antisana Region (Ecuador)**

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ABSTRACT

9 The Ecuadorian Andes are characterized by a complex spatiotemporal vari-
10 ability of precipitation. Global circulation models do not have sufficient hor-
11 izontal resolution to realistically simulate the complex Andean climate and
12 in situ meteorological data are sparse; thus, a high-resolution gridded precip-
13 itation product is needed for hydrological purposes. The region of interest
14 is situated in the center of Ecuador and covers three climatic influences: the
15 Amazon basin, the Andes and the Pacific coast. Therefore, regional climate
16 models are essential tools to simulate the local climate with high spatiotempo-
17 ral resolution; this study is based on simulations from the Weather Research
18 Forecasting (WRF) model. The WRF model is able to reproduce a realis-
19 tic precipitation variability in terms of the diurnal cycle and seasonal cycle
20 compared to observations and satellite products; however, it generated some
21 nonnegligible bias in the region of interest. We propose two new methods for
22 precipitation bias correction of the WRF precipitation simulations based on in
23 situ observations. One method consists of modeling the precipitation bias with
24 a Gaussian process metamodel. The other method is a spatial adaptation of the
25 cumulative distribution function transform approach, called CDF-t, based on
26 Voronoi diagrams. The methods are compared in terms of precipitation occur-
27 rence and intensity criteria using a cross-validation leave-one-out framework.
28 In terms of both criteria the Gaussian process metamodel approach yields bet-
29 ter results. However, in the upper parts of the Andes (>2000 m), the spatial
30 CDF-t method seems to better preserve the spatial WRF physical patterns.

31 1. Introduction

32 The Andes Cordillera forms a natural orographic barrier along the western coast of the South
33 American continent, causing a complex spatiotemporal distribution of precipitation (e.g., Garreaud
34 1999; Espinoza et al. 2009). The spatial precipitation distribution is characterized by strong ele-
35 vational gradients, with the eastern and western sides of the Andes exhibiting higher precipitation
36 values than the high-elevation mountain peaks where the climate is relatively dry (see Fig. 1; e.g.,
37 Bendix and Lauer 1992). We distinguish three different climate regions in Ecuador: the Pacific
38 coast, the Andes and the Amazon. Each side of the Andes is influenced by different atmospheric
39 processes. The western plains of Ecuador are strongly influenced by the sea surface temperature
40 variability of the Pacific Ocean. For instance the occurrence of ENSO (El Niño Southern Oscil-
41 lation) events on an interannual timescale produces strong temperature and precipitation anomalies
42 and significant socioeconomic issues (e.g., Rossel et al. 1999; Vuille et al. 2000; Rabatel et al.
43 2013; Vicente-Serrano et al. 2017). In the eastern part of the Andes, the moisture mainly comes
44 from the Atlantic Ocean and water recycling through evapotranspiration over the humid Amazo-
45 nian rainforest plains. In the Andes the interannual precipitation variability is influenced by both
46 tropical Pacific and Atlantic sea surface temperature anomalies (e.g. Vuille et al. 2000; Espinoza
47 et al. 2011). On the seasonal timescale, the precipitation variability is very complex and can be
48 characterized by one or two rainfall seasons. On the Pacific coast, one rainfall season is generally
49 described (e.g., Bendix and Lauer 1992; Vicente-Serrano et al. 2017) whereas two rainfall seasons
50 are observed in most parts of the Andes (e.g., Bendix and Lauer 1992; Vicente-Serrano et al. 2017)
51 and in the Amazon plains of Ecuador (e.g., Laraque et al. 2007; Espinoza et al. 2009) and these
52 rainfall seasons occur from March to May, and from October to December. At the regional scale,
53 these two periods correspond to the two annual transition phases of the American monsoon cy-

54 cle, between the mature phases of the North American monsoon system (June to August) and the
55 South American monsoon System (December to February; e.g., Vera et al. 2006). However, there
56 are large disparities at the local scale (e.g., Laraque et al. 2007), due to local atmospheric processes
57 associated with the complex orography of the Andes. The slope of the eastern part of the Andes
58 is also characterized by the presence of local maximum precipitation values called “hotspots” (Es-
59 pinoza et al. 2015), and in these regions the elevational gradients are nonlinear, with the maximum
60 values situated between 500 and 2000 m. Thus, the spatiotemporal variability of precipitation is
61 quite complex in this area, making it challenging to characterize with statistical models.

62 The Antisana glacier culminates at approximately 5760 m, and is located close to the Amazon
63 slope on the eastern side of the Ecuadorian Andes. Quito, the capital of Ecuador, is situated ap-
64 proximately 50 km further west closest to the Pacific side of the Andes. The Antisana region is
65 an important water reserve for the population (Chevallier et al. 2011; Hall et al. 2012; Basantes-
66 Serrano 2015; Buytaert et al. 2017; Pouget et al. 2017). The water resources in this region depend
67 in part on the Antisana glacier, whose mass balance is influenced by several factors, including
68 precipitation variability, (e.g., Favier et al. 2004; Sicart et al. 2011). Recently, a dry trend has been
69 identified in the western Amazon during the last decades, including in the Ecuadorian Amazon,
70 and is particularly strong during austral winter (Espinoza et al. 2009). However, the station den-
71 sity in the Andes is low relative to the complexity of the topography, so the spatial distribution of
72 precipitation is poorly understood (Buytaert et al. 2006; Rollenbeck and Bendix 2011; Manz et al.
73 2017). Precipitation in the highest elevation zones is particularly uncertain, as there are few sta-
74 tions located above 3500 m (see Fig. 1 and Table 1). Thus, to understand how the water resources
75 of this region might change in the future, an essential first step is to establish a spatially complete
76 picture of current-day precipitation.

77 In the Andes, global circulation models (GCMs) do not have sufficient horizontal resolution to
78 realistically simulate the complex Andean climate (IPCC 2013). For this reason, regional climate
79 models (RCMs) are essential for simulating the local climate with high spatiotemporal resolution.
80 In this study the Weather Research Forecasting (WRF) model is used. Several previous studies
81 have used the WRF model in the Andes, including, the works developed by Ochoa et al. (2014),
82 Ochoa et al. (2016), Mourre et al. (2016), Junquas et al. (2017). Mourre et al. (2016) and Ochoa
83 et al. (2016), compared WRF simulations to rainfall products derived from satellite products and
84 in situ stations in the Peruvian Andes and in the Ecuadorian Andes, respectively. Whereas the
85 WRF model is able to reproduce a realistic precipitation variability in terms of the diurnal cycle
86 and seasonal cycle compared to observations and satellite products, these studies have also iden-
87 tified quantitative precipitation biases in the Andes, in terms of intensity (precipitation amounts)
88 and occurrence (rainy/non-rainy days). Thus, before using WRF outputs in climate impact stud-
89 ies, the application of bias correction methods of the simulated precipitation is crucial (Vrac and
90 Friederichs 2015).

91 In the Andes the orographic gradients play an important role on the atmospheric processes. The
92 WRF model is able to reproduce two different spatial-scale mechanisms associated with the pre-
93 cipitation distribution (e.g., Ochoa et al. 2014; Mourre et al. 2016; Junquas et al. 2017): local-scale
94 (e.g., valley and mountain winds) and synoptic-scale (e.g. low-level jet east of the Andes) circula-
95 tion. The three previously defined climate regions in Ecuador (Pacific coast, Andes, and Amazon)
96 are differently affected by these processes. Therefore, it is reasonable to think that the precipi-
97 tation biases simulated by the WRF model could also be affected differently by these different
98 atmospheric processes in each climate region. Thus, it is crucial to develop different statistical
99 methods taking into account this particular climate distribution, by focusing on the spatial precip-
100 itation bias distribution.

101 Our main objective in this study is to statistically correct the WRF outputs of precipitation at the
102 daily timescale, during the two-year period in the Antisana region (2014-2015). Considering the
103 unique climate characteristics of the region and the few observations, we decided to develop new
104 methods by adapting statistical tools from the literature. The first method consists of modeling the
105 precipitation bias with a Gaussian process. This approach is also known as kriging in geostatistics
106 and takes into account the spatial statistical structure of a variable of interest. Several studies have
107 been developed to correct the precipitation bias based on Gaussian process models. For example,
108 Hanchao Wong et al. (2012) developed a bias correction of radar rainfall based on the kriging ap-
109 proach in Thailand, Müller and Thompson (2013) performed a bias adjustment of satellite rainfall
110 in Nepal, they used kriging to interpolate precipitation from in situ measures, and Moure et al.
111 (2016) performed a precipitation interpolation based on kriging using as external drift the WRF
112 simulation in the Cordillera Blanca (Peru). In Ecuador, the kriging method was already tested as a
113 spatial interpolation method on the Pacific coast (Ochoa et al. 2014) and in the highlands (Buytaert
114 et al. 2006) with in situ stations. They showed that using kriging interpolation with elevation as
115 the external drift significantly improved the performance of the method in these regions. In our
116 study, the novelty of our approach is to apply kriging to the daily precipitation bias instead of
117 the precipitation amount, as is classically done. We will show that this adaptation is particularly
118 useful in regions where different precipitation regimes coexist, as is the case in our region with the
119 Amazon and Andean climates.

120 The second approach generalizes the quantile-quantile method (e.g., Déqué 2007) and is based
121 on the cumulative distribution function transform (hereafter CDF-t) with Singularity Stochastic
122 Removal approach developed by Vrac et al. (2016). The probabilistic approach “cumulative dis-
123 tribution function-transform” (hereafter CDF-t) has been used in many applications, including
124 correction of the punctual daily wind speed and regional downscaling (e.g., Michelangeli et al.

2009; Vrac and Vaittinada 2017). This approach has also been applied to correct the biases of different atmospheric variables; such as temperature, precipitation and relative humidity (e.g., Colette et al. 2012; Vrac et al. 2012). Vrac et al. (2016) proposed a modification of the CDF-t method for bias correction, specifically designed for precipitation, called “Singularity Stochastic Removal” (hereafter SSR). The motivation for developing an approach specialized for precipitation is because of its particular property in terms of a large number of zeros (non-precipitation events) in a daily time step. The principal advantage of this approach is that it allows us to correct biases while avoiding separating the correction in terms of occurrence (number of rainy days) and intensity of precipitation (quantity of precipitation). Previously, the SSR approach has been used to correct heat waves over France, as implemented by Ouzeau et al. (2016), and in a multivariate quantile mapping bias correction context to correct surface meteorological variables from regional climate model outputs across a North American domain (Cannon 2017).

The CDF-t is a variant of the quantile-mapping technique, which consists of mapping a model output x with cumulative distribution function (CDF) F_X , to its corresponding observation y with CDF F_Y , through a function T (Piani et al. 2010; Vrac et al. 2016). More precisely, considering $T = F_{Y^{-1}} \circ F_X$, where F_Y^{-1} is the generalized inverse of F_Y , thus we obtain $y = T(x)$ in the sense that $F_Y = F_{T(X)}$ (y is distributed as $T(x)$).

Then, T can be modeled either parametrically or nonparametrically, and estimated from the data. If the data are stationary and consist of n independent realizations of x (*resp.* y), then T can be estimated by $F_{Y,n}^{-1} \circ F_{X,n}$ with $F_{X,n}$ (*resp.* $F_{Y,n}$) representing the empirical CDF of x (*resp.* y). In that case, the procedure is known as the empirical mapping procedure.

Usually, the CDF-t approach is used to correct model predictions for future periods. We propose in this paper a spatial adaptation of the CDF-t approach from a point scale correction to a correction on any grid point, partitioning the region of interest using a Voronoi diagram of the stations (see

149 Section 3 for more details). Voronoï diagrams, also known as Thiessen polygons, have been widely
150 used in meteorological applications. As for example in (Buytaert et al. 2006), spatial interpolation
151 of precipitation with Thiessen polygons in the south Ecuadorian Andes is performed. In (Ly et al.
152 2011), spatial interpolation is performed in the Ourthe and Ambleve catchments in Belgium.

153 This paper is organized as follows. In Section 2 we present the data used in the study and the
154 WRF simulation characteristics. In Section 3 we describe the new methods of precipitation bias
155 corrections. We analyze the results and the intercomparison between them in Section 4. Finally,
156 we summarize the main results and conclude in Section 5.

157 **2. Data**

158 *a. In situ data*

159 We use daily data from 26 in situ meteorological stations with elevations that range from 1110
160 to 4812 m, during the 2014-2015 period. All of the stations with the exception of station 26 were
161 installed and are managed by the National Service of Meteorology and Hydrology of Ecuador
162 (INAMHI). The stations from the INAMHI are of a tipping bucket type, and the highest is station
163 17 at 4009 m. The INAMHI data quality is routinely controlled, using the standard procedures in
164 use by Met services worldwide. Based on in situ observations, Francou et al. (2004) determined
165 the snowfall/rainfall limit at 4900 m close to the snout of the Ecuadorian glaciers. This elevation
166 corresponds to a temperature threshold equal to 0.5° . All the stations from the INAMHI network
167 are situated below 4009 m, so we do not observe snowfall at the INAMHI' stations (see Table 1).
168 Station number 26, belonging to the SNO GLACIOCLIM, is situated at 4812 m. Snowfall is fre-
169 quent at this altitude, and some care must be taken to reduce the uncertainty of the measurement.
170 First, the gauge should be adapted to measure any type of hydrometeor (solid or liquid). Second

171 the problem of undercatch, principally caused by wind must be addressed. In the present study,
172 we used data issued from Geonor gauge; this type the gauge is a weighting device specifically
173 designed to measure all the hydrometeor types and is suitable for both solid and liquid precip-
174 itation. To reduce the problem of under catch principally caused by wind effects, we use the
175 correction proposed by Forland et al. (1996), depending on the air temperature and wind velocity.
176 The detailed procedure for the data treatment is provided in Wagnon et al. (2009). At the regional
177 scale for the whole Andean zone defined in the study, the snowfalls are not very important if one
178 considers the surface of the ground located higher than 4900 m (less than 1% of the total area).

179 Figure 1 shows a map with the locations of the stations. The study area is divided into three
180 regions corresponding to three regions of Ecuador (see Section 1): the region located on the Pacific
181 coast side (hereafter Pacific coast) formed by stations 2, 22 and 23; the Amazon formed by stations
182 19 and 25; and the Andes, formed by the remaining ones (21 stations). Most stations are located
183 in the Andes (81%), with 11% on the Pacific coast and 8% in the Amazon. Table 1 presents
184 a description of the location and accumulated precipitation for the period 2014-2015 for each
185 meteorological station. The meteorological stations located in the Amazon registered the highest
186 total precipitation values (with total precipitation greater than 6000 mm in the two years).

187 Because very few in situ stations were available in this region, we included two stations (num-
188 bers 12 and 18) situated very close to the limits of the domain (less than 4km in latitude) and at
189 the same elevation. Because the main idea of this study is to test bias correction methodologies,
190 we decided to include these two stations for these tests, by assigning their corresponding model
191 grid latitudes as 0.01 to avoid the boundary zone of the model (see Section 2c). Originally, sta-
192 tion number 12 was situated at the latitude 0.05 and station number 18 was situated at the latitude
193 0.03, corresponding to 4km and 2km from the model limit, respectively. We performed statisti-
194 cal analysis (not shown) that confirmed that these precipitation timeseries of the WRF-1km grid

195 points are significantly correlated to the corresponding in situ stations timeseries in terms of oc-
196 currence and intensity, even considering some km lags, highlighting that precipitation variability
197 is homogeneous in this small region.

198 *b. CHIRPS satellite product*

199 Satellite-based rainfall estimates such as CHIRPS (Climate Hazard Group 1981; Funk et al.
200 2015) provide an opportunity for a wide range of hydrological applications, from water resource
201 modeling to monitor of extreme events, such as droughts and floods. CHIRPS is a continental
202 rain data set that combines satellite and rain gauges data with a spatial resolution of $0.05^{\circ} \times 0.05^{\circ}$.
203 CHIRPS uses the global cold cloud duration (CCD) as a thermal infrared method to estimate
204 the global precipitation. Then, the product TRMM-3B42 V7 is used to calibrate the precipita-
205 tion estimated by the global CCD. Finally, gauge stations are used to calibrate the estimations of
206 precipitation (Paccini et al. 2018). Recent studies note that, at daily time steps or for arid envi-
207 ronments, important biases exist in these rainfall estimations (Herold et al. 2017; Paredes-Trejo
208 et al. 2017). Furthermore, Bai et al. (2018) used the CHIRPS product in mountainous regions in
209 China and concluded that the ability of CHIRPS to detect snowfall was limited. More generally,
210 this product has known biases, including underestimation of extreme precipitation events (Funk
211 et al. 2015). In our study, the use of the precipitation satellite product CHIRPS for the period of
212 2014-2015 allows for a graphical evaluation of the corrected gridded precipitation products. In-
213 deed, this product provides good spatial patterns at seasonal or annual scales (Zambrano-Bigiarini
214 et al. 2017). Thus, we use this dataset for a spatially complete qualitative comparison, but only in
215 an approximate sense.

216 *c. WRF simulation and its biases*

217 The WRF model version 3.7.1 (Skamarock et al. 2008) is used to simulate high-resolution pre-
218 cipitation for the period 2014-2015 in the studied region. The model is nonhydrostatic and uses
219 a terrain-following vertical coordinate (sigma). The WRF model is established with 4 one-way
220 nested domains (27 km, 9 km, 3 km, and 1 km; see Fig. 2). The outer domain is forced by the
221 NCEP-FNL reanalyses ($1^\circ \times 1^\circ$). The simulation outputs of the innermost domain ($1\text{km} \times 1\text{km}$)
222 are used for this study. The in situ data for each station are compared with the closest 1km grid
223 point of the WRF simulation. As mentioned in Section 2a, for two stations (numbers 12 and 18),
224 the closest inner-domain gridpoint was considered to avoid the northern lateral boundary zone of
225 the model (5 gridpoints of specified and relaxation zone; see Fig. 2d). The four domains are con-
226 figured with 30 sigma levels in the atmosphere, and the top model is configured at 50hPa, as it was
227 already used in previous studies in the tropical Andes (Junquas et al. 2017; Moya-Álvarez et al.
228 2018). The output time resolutions are 6 h, 3 h, 3 h, and 1 h for the first, second, third and fourth
229 domain, respectively.

230 Some options for the dynamical and physical parameterizations were previously tested to pro-
231 vide better precipitation results in the region of interest (not shown). The chosen parameterizations
232 are described as follows. We use the Yonsei University scheme (Hong et al. 2006) as the plane-
233 tary boundary layer option, with a wind topographic correction for the complex surface terrain
234 (Jiménez and Dudhia 2012), that has already been used in previous studies using the WRF model
235 in the Andes (Mourre et al. 2016; Junquas et al. 2017). The Microphysical parameterization is
236 from Lin et al. (1983), and the cumulus scheme is from Grell and Dévényi (2002). Preliminary
237 tests have been performed with other parameterizations, and this configuration was chosen be-
238 cause the precipitation bias in the Andes was less pronounced (not shown). We decided to employ

the cumulus parameterization in the four domains because in our tests, the convection-permitting experiment (no cumulus scheme activated at 3 km and 1 km) exhibit the greatest bias with a precipitation overestimation of more than 300% in the Andes compared to station data (not shown). This result confirms the results of a recent paper that did not find precipitation improvements using convection permitting in WRF forecasting simulations in the Peruvian Andes region (Moya-Álvarez et al. 2018).

As the surface model, we use the Noah multi-physics model with a snow option (snf_opt=2; Niu et al. 2011; Yang et al. 2011) as previously tested in the Cordillera Blanca in Peru (Mourre et al. 2016). The longwave and shortwave radiation options are RRTM (Mlawer et al. 1997) and Dudhia scheme (Dudhia 1989), respectively. The surface layer parameterization is MM5 similarity (Paulson 1970). We used the SRTM (Shuttle Radar Topography Mission; Farr et al. 2007) digital elevation model instead of the USGS (United States Geological Survey) data as topographic forcing, as suggested by preliminary studies.

We compared the in situ observations and the WRF simulations and found that they are biased (see Figure 3). The mean bias per station is 1.89 mm day^{-1} during the two years with, a minimum of 0.04 mm day^{-1} (achieved at station 17) and a maximum of 9.72 mm day^{-1} (station 2). During 2014, the mean relative bias is an underestimation of 20%, its maximum underestimation is 80% (station 2) and the maximum overestimation is registered at station 6 (47%). During 2015, the mean relative bias is an underestimation of 42%, with a maximum underestimation of 85% (station 2), and the maximum overestimation is 23%, registered at station 13.

The biases are more evident in the Amazon, where underestimations of approximately 8.20 and 6.96 mm day^{-1} are obtained for stations 19 and 25. The biases of the 2014 and 2015 periods are slightly different because during 2014, there is strong overestimation of the simulated precipitation at some stations of the Andes (stations 3, 6 and 18), in contrast to 2015, when underestimation are

obtained for most of the stations (except for 13 and 17). It is clear from these figures that the spatial bias variability strongly depends on the period under consideration. The spatial distribution of the bias in 2015 (Fig. 3b) appears more homogeneous than the one in 2014 (Fig. 3a). This contrast is explained by different local influences of atmospheric processes on the interannual variability in the region of the Andes. The interannual variability is part of the complexity of the spatiotemporal precipitation distribution in the Ecuadorian Andes. Note that some biases identified in the WRF simulations could potentially be caused by errors in the in situ observations.

3. Bias correction methods

Two methods for bias correction are adapted and analyzed in this study. The first one is to model the WRF bias with a Gaussian process model, also known as kriging, and the second one is a time series preprocessing and spatial adaptation of the CDF-t method. The methods are described in this section (parts a and b), and we present the criteria used to evaluate the performance of the two approaches that are used (part c) in the results section (Section 4).

a. Gaussian process modeling

The first method implemented is to model the WRF biases using a Gaussian process model; Figure 4 presents the flowchart of our method. In the following, we define bias as follows:

$$\text{BIAS} = \text{WRF simulation} - \text{Observation}. \quad (1)$$

Then, at in each point where there is no observation, we obtain a prediction of the bias ($\widehat{\text{BIAS}}$) and we compute the predicted precipitation ($\widehat{\text{Precip.}}$) value as follows:

$$\widehat{\text{Precip.}} = \text{WRF simulation} - \widehat{\text{BIAS}}. \quad (2)$$

281 We refer to the work of Marrel et al. (2008) for a presentation of Gaussian process modeling
 282 (also see the work of Oakley and O’Hagan (2002)). Consider that n observations of a phenomenon
 283 are registered at n different locations (for example, the bias precipitation registered in n stations
 284 of the region under study). We consider in the following that each observation $y(x)$ is registered
 285 at point $x = (x_1, x_2) \in \mathbb{R}^2$ (the coordinates of x correspond to the longitude and latitude of the
 286 station), endowed with the usual Euclidean distance. The set of points where the observations are
 287 collected is denoted by $x_s = (x^{(1)}, \dots, x^{(n)})$ with $x^{(1)}, \dots, x^{(n)} \in \mathbb{R}^2$ (in our study, each x corresponds
 288 to a station). The set of observations of the phenomenon is denoted by $y_s = (y^{(1)}, \dots, y^{(n)})$ with
 289 $y^{(i)} = y(x^{(i)})$. The Gaussian process modeling consists of representing $y(x)$ as a realization of a
 290 random function $Y(x)$ such that:

$$Y(x) = f(x) + Z(x) + U(x), \quad (3)$$

291 where $Z(x)$ is a centered stationary Gaussian process; $U(x)$ represents the noise in the obser-
 292 vations and is a centered stationary Gaussian process with a diagonal covariance structure; and
 293 $f(x)$ is a deterministic function that represents the tendency, also known as the external drift, lin-
 294 ear combinations of longitude, latitude and elevation are commonly used. More generally, it is
 295 constructed as a finite linear combination of k elementary functions:

$$f(x) = \sum_{j=0}^k \beta_j f_j(x) = F(x)\beta \quad (4)$$

296 where $\beta = (\beta_0, \dots, \beta_k)^T$ is the regression parameter vector and $F(x) = (f_0(x), \dots, f_k(x))$. The
 297 function $f(x)$ allows the addition of an external drift into the modeling, and this is advantageous
 298 because it allows a nonstationary global modeling framework; in other words the variable Y does
 299 not need to be stationary but the variable Z is assumed to be stationary.

The Gaussian centered process $Z(x)$ has the following a covariance function:

$$\text{Cov}(Z(x), Z(u)) = K(x - u) = \sigma^2 R(x - u), \quad (5)$$

where $x, u \in \mathbb{R}^2$ (in our application, u also corresponds to the coordinates longitude and latitude of a station), σ^2 is the variance of Z , and R is its correlation function. The process Z is stationary because it is considered that its correlation function depends only on the difference between x and u .

In this study, we used the Matérn covariance functions because they are stationary and commonly used in spatial statistics studies due to their flexibility (Paciorek and Schervish 2006); and they are defined follows:

$$K(x, u) = \frac{1}{\Gamma(\nu)2^{\nu-1}} \left[\frac{\sqrt{2\nu}}{\kappa} |x - u| \right]^\nu K_\nu \left(\frac{\sqrt{2\nu}}{\kappa} |x - u| \right), \quad (6)$$

where K_ν is the modified Bessel function of second kind of order $\nu > 0$, κ is a positive parameter that represents the characteristic length scale and Γ is the Gamma function (Rasmussen and Williams 2005). The Euclidean distance, written as $|x - u|$, is used.

The aim of Gaussian process modeling is to estimate the prediction of Y for a new grid point x^* . In our study, Gaussian process modeling is applied to estimate the bias at grid points at which there is no station. In our application, first, the bias is computed for annual averages to assess the accuracy of four models constructed by the combination of three commonly used drifts (longitude; latitude and elevation) and to choose one of them. Here-after, they are referred to as the GP model with drift longitude, latitude and elevation (GP+longitude+latitude+elevation), the GP model with drift longitude and latitude (GP+longitude+latitude), the GP model with drift longi-

318 tude (GP+longitude) and the GP model with drift elevation (GP+elevation). Then, we computed
319 the daily bias using the GP with the selected drift to obtain a corrected daily precipitation product.

320 *b. Spatial adaptation of the CDF-t method*

321 Historically, the CDF-t method has been applied as a statistical downscaling method and to
322 correct future time series from GCMs outputs. In our study, the CDF-t method aims at relating
323 CDFs of a climate variable (here the precipitation) from WRF simulation outputs to the CDF of
324 this variable from the in situ observation. However, instead of applying the correction over future
325 time series, we adapt the method to correct the gridpoints of the domain, even where there is no
326 associated observation. We call this approach a spatial adaptation of the CDF-t method. The main
327 idea is to partition the region under study (see Fig. 1) into neighboring sub-regions, in such a
328 manner that every subregion contains a station. We are going to assume that the precipitation
329 biases in these subregions behave similarly.

330 To define the subregions, we divide the region using a partition based on Voronoï diagrams.
331 This method is a simple way to define subregions, that is, applicable to any mountain region with
332 few complete in situ precipitation time series, as in our case. In addition, as there is no spatial
333 smoothing, it has the advantage of conserving the spatial coherence of the physical processes
334 simulated by the WRF model inside each subregion. Another advantage of using Voronoï diagrams
335 is their simplicity and low computational cost, which allow them to be used with large volumes of
336 data.

337 At a given station s , let us denote X_t^s the model simulation at time t and Y_t^s its corresponding
338 observation. The time series under study are nonstationary and autocorrelated, hence the standard
339 empirical mapping cannot be used directly (see Section 1). Indeed, we performed the usual statisti-
340 cal hypothesis testing procedures to detect nonstationarity: the Kwiatkowski Phillips Schmidt Shin

test (Kwiatkowski et al. (1992); KPSS where H_0 : The time series is stationary), and the Mann-Kendall test (Mann (1945); Kendall (1948); H_0 : The time series do not have a monotonic trend). The p-value results of the KPSS and Mann-Kendall tests are less than 0.1 and 0.05, respectively, for all the observed and simulated time series, meaning that the time series are nonstationary due to a unit root (autocorrelation close to 1) and dependent. It is thus necessary to perform differentiation and subsampling. More precisely, we applied the following preprocessing: we calculated $\Delta X_t^s = X_t^s - X_{t-1}^s$ and $\Delta Y_t^s = Y_t^s - Y_{t-1}^s$ to stationarize the time series, and we used subsampling to eliminate the autocorrelation. The manner in which we performed subsampling is the following: as the autocorrelation length was estimated to $k = 2$, we skipped one observation out of two.

As already mentioned, the main issues of bias correction for precipitation data is the treatment of the rainfall occurrences. To solve this issue Vrac et al. (2016) proposed changing the null precipitation data for a uniform distribution. In our case, we corrected the differentiated time series of precipitation, thus we adapted the SSR to our framework. More precisely, we performed the following steps on our data:

Step 1.- Determinate a threshold θ such that:

$$\theta = \min \left(\inf_{t \geq 1, |\Delta X_t^s| \neq 0} \{|\Delta X_t^s|\}, \inf_{t \geq 1, |\Delta Y_t^s| \neq 0} \{|\Delta Y_t^s|\} \right) \quad (7)$$

Step 2.- Each time $\Delta X_t^s = 0$ (*resp.*, $\Delta Y_t^s = 0$), we simulate a value v from the uniform distribution $U[-\theta, \theta]$ and we replace ΔX_t^s (*resp.*, ΔY_t^s) with the sampled value.

Such a step avoids separating the correction of the occurrences from the one of the intensities. (Vrac et al. 2016).

Step 3.- Nonparametrically estimate the mapping $F_{\Delta Y^s}^{-1}(F_{\Delta X^s})$ using e.g., the R package developed by Vrac (2015) (see also Michelangeli et al. (2009)). The mapping will be denoted by \hat{T}^s in the following.

In this paper, we do not aim at correcting the bias for future predictions, but we want to correct the bias at any grid point where no observation is available.

Therefore, we construct a Voronoï diagram based on seeds composed with the stations. For each station (seed) there is a corresponding region consisting of all points closer to that seed than to any other. In this manner, we obtain as many regions as the initial number of stations, let us say \mathcal{S} . For $s = 1, \dots, \mathcal{S}$, we construct following Step 3 a mapping \hat{T}^s from time series X_t^s and Y_t^s . We then assume that the mapping is constant on each Voronoï cell. We then proceed with the following steps:

Step 4.- At any grid point, let us consider the closest station s . We consider the time series ΔZ_t , where Z_t denotes the WRF simulation at time t . If the grid point coincides with station s , then $Z_t = X_t^s$. We apply the following bias correction:

$$V_t = Z_{t-1} + \hat{T}^s(\Delta Z_t) \quad (8)$$

Step 5.- The bias corrected data V_t lower than θ are set to 0. This step allows us to recover the correct occurrence of 0 precipitation.

As an illustration of the procedure, Figure 5 shows for 3 stations (one for each region) the original time series (X_t and Y_t), the differentiated ones (ΔX_t and ΔY_t) and the CDFs of the observation, simulation and CDF-t correction (more details are presented in Section 4b).

379 *c. Evaluation criteria to compare the two approaches*

380 To compare the accuracy of the rainfall products created by these two methods (Gaussian pro-
381 cess modeling and spatial CDF-t approach), we have computed various criteria concerned with
382 occurrences (number of rainy/non-rainy days) and intensity of precipitation (precipitation quan-
383 tity). These criteria are commonly used in the literature; for example, they were used in the works
384 of Maussion et al. (2011), Ochoa et al. (2014), Moure et al. (2016) and, Vrac et al. (2016).

385 CRITERIA RELATED TO THE OCCURRENCE

386 A day is considered as a “rainy day” if its daily precipitation value is greater than 1 mm day⁻¹.
387 Note that other threshold values were tested, but the best agreement between the WRF model
388 and in situ observations was obtained with 1 mm day⁻¹ (not shown). In the following, several
389 measures that depend on the following four major parameters are used:

390 **True Positive (TP):** Rainy day identified by WRF as a rainy day.

391 **True Negative (TN):** Non-rainy day identified by WRF as a non-rainy day.

392 **False Positive (FP):** Non-rainy day identified by WRF as a rainy day.

393 **False Negative (FN):** Rainy day identified by WRF as non-a rainy day.

394 The false alarm rate (FAR) is defined as the incorrect number of rainy days simulated divided
395 by the total number of rainy days simulated:

$$FAR = \frac{\#FP}{\#FP + \#TP} \quad (9)$$

396 The probability of detection (POD) is defined as the ratio between the number of rainy days
397 simulated correctly and the total number of rainy days observed:

$$POD = \frac{\#TP}{\#TP + \#FN} \quad (10)$$

398 The probability of false detection (PODF) is the ratio between the number of rainy days incor-
 399 rectly simulated to the number of non-rainy days of the observation:

$$PODF = \frac{\#FP}{\#FP + \#TN} \quad (11)$$

400 And finally, the Heidke skill score (HSS) is calculated as:

$$HSS = \frac{S - S_{ref}}{1 - S_{ref}}, \quad (12)$$

401 where $S = \frac{\#TP + \#TN}{n}$ and $S_{ref} = \frac{(\#TP + \#FP)(\#TP + \#FN) + (\#FP + \#TN)(\#FN + \#TN)}{n^2}$. It could be interpreted
 402 as the ability of the simulation to be better or worst than a random simulation. A perfect product
 403 should have a FAR value of 0, a POD value of 1, a 0 PODF value and an HSS value of 1.

404 CRITERIA RELATED TO THE INTENSITY

405 The following criteria are used to evaluate gridded products accuracy in terms of intensity: the
 406 Kolmogorov-Smirnov test (KS) is a nonparametric test to compare two distributions; the maximal
 407 difference between them is calculated. The Spearman correlation coefficient, the root mean square
 408 error (RMSE) and the mean bias are computed. It is important for the precipitation also to know
 409 the percentage of data that is greater than the 0.95 percentile of the observation and in the case
 410 of a good precipitation product, it should be close to 5% (here-after referred as Q₉₅). Finally, the
 411 predictivity squared correlation coefficient Q₂ is computed. It measures the predictive ability of

412 the statistical model.

$$\text{mean bias} = \frac{1}{n} \sum_{i=1}^n (\hat{x}_i - x_i), \quad (13)$$

$$\text{RMSE} = \sqrt{\frac{1}{n} \sum_{i=1}^n (\hat{x}_i - x_i)^2}, \quad (14)$$

$$Q_2 = 1 - \frac{\sum_{i=1}^n (x_i - \hat{x}_i)^2}{\sum_{i=1}^n (\bar{x} - x_i)^2}, \quad (15)$$

413 where \hat{x}_i is the prediction of the precipitation (using one of the approaches described before)
 414 at station i , x_i is the observed precipitation at the same station i and \bar{x} is the observed mean.
 415 These criteria should be computed on a set of stations independent from the ones used to learn
 416 the statistical model. However, we used all the stations to train the model (Gaussian Process or
 417 CDF-t); thus (13), (14) and (15) will be computed by cross-validation in the following. The leave-
 418 one-out cross-validation consists of splitting the data into two groups: a group composed with all
 419 the stations except one, which is used as learning sample, and another group whose sole element
 420 is the remaining station, on which the model is validated. Then, the procedure is averaged on all
 421 such leave-one-out splits. For example, for Q_2 :

$$1 - \frac{\sum_{k=1}^n (x_k - \hat{x}_k^{-(k)})^2}{\sum_{k=1}^n (\bar{x} - x_k)^2} \quad (16)$$

422 where $\hat{x}_k^{-(k)}$ is the prediction at station number k , when the model is trained by the $n - 1$ remain-
 423 ing stations.

424 4. Results

425 The principal results that we obtained are presented in this section. Subsections a and b are
 426 devoted to the results for the GP modeling and spatial CDF-t. In subsection c we present the

intercomparison between both approaches. All the analysis and methods implementation were performed in R (R Core Team 2015).

a. Gaussian process modeling

We implemented the GP models using the R package `gstat` developed in (Pebesma 2004; Gräler et al. 2016). We evaluated the four GP models to select an external drift using a cross-validation leave-one-out framework. Table 2 presents the cross-validation results for the four corrected precipitation gridded products. All of the four proposed GP models exhibit better results than the uncorrected WRF outputs in terms of the criteria of Section 3c (mean, bias, RMS and correlation; see Table 2). However, in general, the GP+longitude+latitude model obtains the best results in terms of all of the criteria (bias, RMSE, correlation and Q_2). In terms of predictability (Q_2), the GP+longitude+latitude model exhibits the highest values, but the GP+elevation model values are not significantly different. The GP+longitude+latitude+elevation model yields the lowest predictability values. Thus, this last model most likely overfits the data, whereas more parsimonious models have better predictive ability.

Analyzing the two years separately, it is found that the predictive ability is better in 2015 for the four models. However, for some criteria the values are not significantly different for each year, such as for RMSE values for GP+longitude and for GP+elevation. In addition, for the GP+elevation model the mean bias is higher for 2015 than for 2014. Longer periods are necessary to adequately analyze the choice of the external drift parameters on the results, which is beyond of the scope of this study considering that we only have available data spanning a two-year period. Therefore, we chose the GP+longitude+latitude model and used a Matérn covariance function to correct the daily precipitation by using separate daily variograms described in (Gräler et al. 2012) because this model yields the best results for both years of analysis. Figure 6a shows

the mean daily precipitation of the gridded products WRF and CHIRPS, and the cross-validation results of the GP compared to the mean daily precipitation of the station. Their respective linear regression lines are drawn. The R^2 value of the linear regression of WRF is 0.38, that of GP is 0.62 and that of CHIRPS is 0.70, which means that the results of the cross-validation of GP are better than WRF. Figures 7a,b,c show the accumulated precipitation of WRF, the GP correction in cross-validation and the precipitation registered at the three stations (Fig. 7a shows Pacific coast station 22; Fig. 7b shows Andes station 26, and Fig. 7c shows Amazon station 25). At the Pacific coast and the Andes stations, the corrections yield an overestimation of the precipitation (see Fig. 7a and Fig. 7b), and at the Amazon station, the correction increases the precipitation to correct the underestimation simulated by WRF (see Fig. 7c).

b. Spatial CDF-t

The procedure described in Subsection 3b is applied. The Voronoï diagram is calculated (see Fig.10f) and maps of mean of daily precipitation are presented in Fig. 10 (the stations), 10b (CHIRPS), 10c (WRF), 10d (GP) and 10e (CDF-t). The Voronoï diagram borders are marked in the Amazon due to the inhomogeneous distribution of the stations and also high underestimated precipitation in this region (for example, approximately $3000 \text{ mm year}^{-1}$ at station 25). On the Pacific coast, the border of the polygon associated with station 22 is marked because it has recorded higher precipitation values. On the contrary, the polygon borders around the Andes are not visible in most of the cases because the biases in the Andes were quite homogeneous (see Figures 3a and 3b). Therefore, in the Andes, the spatial CDF-t approach yields realistic results, by conserving the precipitation physical gradients simulated by WRF. A homogeneous station distribution could increase the accuracy of the method by taking into account more physical variables in addition to geometrical properties. Figure 6b shows the mean daily precipitation of the gridded products

WRF, CHIRPS, and CDFt and their linear regression lines. The R^2 coefficient of CDFt (0.89) is better than that of WRF (0.38). Figures 7d,e,f shows the accumulated precipitation of WRF, the spatial CDF-t correction and the precipitation registered in the observation of three regions stations (Fig. 7d shows Pacific coast station 22; Fig. 7e, shows Andes station 26; and Fig. 7f Amazon station 25). At the Pacific coast station, the WRF simulation and its correction are similar; there is a slight increase in the precipitation in the correction to obtain a value closer to the observation (see Fig. 7d). The correction applied to the Andes station is also slight because the biases registered at these stations are low (see Fig. 7e). The correction for the Amazon station is more evident due to the high underestimation obtained by WRF (see Fig. 7f).

c. Intercomparison between the two methods

After analyzing separately the implementation of the spatial CDF-t approach and the GP correction methods, we now present the an intercomparison between these different bias corrections using cross-validation leave-one-out. We use the criteria from the Subsection 3c to compare the two correction approaches (GP and spatial CDF-t) and WRF. The GP model used for these results is GP+latitude+longitude, as it was shown to outperform the other GP models tested in Table 2.

The criteria related to the occurrence are shown in Figure 8. The spatial CDF-t method yields results similar to WRF in terms of the FAR (mean of 0.47 and 0.45, respectively) and PODF criteria (spatial CDF-t has a mean of 0.21 and WRF 0.23); meanwhile the GP result is worst (mean of 0.53 in FAR and 0.51 in PODF). The HSS results are similar for the three spatial products (WRF has a mean of 0.23, spatial CDF-t has 0.21 and GP has 0.22), and the HSS criterion is more stable for GP since its variance is less than those of the other products (GP has a standard deviation of 0.09, spatial CDF-t has 0.12, and WRF has 0.11, see Fig. 8d). The POD criterion is highly improved by GP (0.79 versus 0.49 for the Spatial CDF-t).

496 The results related to the precipitation intensity are shown in Figure 9. The KS criterion is
497 improved with the spatial CDF-t (a mean of 0.21 versus 0.38 for GP) but the results exhibit a high
498 variability (a standard deviation of 0.2, and GP has a standard deviation of 0.15). The RMSE
499 criterion is similar for the two products (spatial CDF-t has a mean of 7.78, GP has 7.16, and WRF
500 has 7.78). However, on the contrary, the Spearman correlation (GP has a mean of 0.38, versus 0.24
501 for spatial CDF-t) and Q_{95} (GP has a mean value of 0.05, versus 0.04 for spatial CDF-t) values are
502 slightly improved in GP.

503 The CHIRPS daily mean map is displayed in Figure 10b. Because of well-known quantitative
504 biases in the tropical Andes (up to 80%; e.g., Espinoza et al. (2015)), we use only this data to visu-
505 ally compare the spatial precipitation patterns. When visually comparing both corrected products,
506 it seems that the GP model (Fig. 10d) is more similar to the satellite than the spatial CDF-t (Fig.
507 10e) in the Andes, mainly due to the sharp discontinuities at the polygon borders on the eastern
508 slope. However, in the Amazon the GP model shows a zone of maximum precipitation in the
509 south-east of the domain that is not observed in the satellite data. However, given that, the satellite
510 data are biased and there are no data in this part of the region, this result could be uncertain. A
511 strong gradient of precipitation is evident in the eastern slope of the Andes in both the GP model
512 and the satellite data. This gradient depends on the elevation and the presence of local atmospheric
513 valleys processes (e.g., Egger et al. (2005); Junquas et al. (2017)). Previous studies have found
514 that the WRF model is able to reproduce some local valley processes in the tropical Andes (e.g.,
515 Murre et al. (2016); Junquas et al. (2017)). Therefore, it is important to take into account that
516 such WRF spatial patterns should be preserved in a bias correction method. This orographic limit
517 is visually well represented with the GP method, compared with the satellite. Whereas the spatial
518 CDF-t is visually unrealistic on the eastern slope of the Andes due to the polygon limits, in the An-
519 des above 2000 m it seems to be able to conserve the spatial patterns of WRF. In addition, the CDF

of the WRF Antisana gridpoint is very similar to the Antisana station CDF (Fig. 5h), and the relative bias is very weak (Fig. 3). We then expect, that in this particular region, no large quantitative bias correction should be applied. However, whereas the spatial CDF-t clearly exhibits very little quantitative correction in this region, the GP model exhibits increased precipitation, generating an overestimation compared to the observations (see Fig. 7a and Fig. 7b). The spatial CDF-t method seems then to be adapted to the upper parts of the Andes (above about 2000 m), where relatively low precipitation values dominate compared to the Amazon precipitation. In the contrast, it is not recommended to use the spatial CDF-t in regions where strong precipitation gradient exists.

5. Conclusions and future work

The aim of this study was to correct the WRF simulation precipitation biases in the studied region. Then, the final gridded products of precipitation will be used as external forcing data for hydrological and glaciological models to understand water resources and glaciers evolution in the Andes. Therefore, two methods of precipitation bias correction were explored and adapted: the first one consisted of modeling the daily WRF biases through Gaussian process (GP) models, and the second one was based on a spatial and time series adaptation of the CDF-t method developed by Michelangeli et al. (2009) and Vrac et al. (2016).

First, four GP models were proposed by using four combinations of external drifts (generally used in studies of this type, including latitude, longitude and elevation variables) to model the annual accumulated bias during the years 2014 and 2015. The accuracy of the GP models was tested in a cross-validation leave-one-out framework. Based on four criteria (Bias, RMSE, Correlation and Q_2), the best model was GP with drift longitude and latitude. Thus, we chose this model to correct the daily precipitation by using separate daily variograms as it is described in (Gräler et al. 2012).

543 We employed the SSR method with a time series adaptation to obtain the CDF estimations
544 and a spatial adaptation to obtain the correction in the region. The methods were compared in
545 terms of criteria related to the occurrence (FAR, POD, PODF, and HSS) and criteria related to
546 the intensity (mean bias, Spearman correlation, KS, RMSE, Q2, and Q₉₅). Compared with the
547 WRF product, the spatial CDF-t approach did not exhibit significant changes, whereas the GP
548 model correction increased the daily rain number and the total accumulated mean, improving
549 (or worsening) significantly some intensity (occurrence) statistical scores. In terms of spatial
550 distribution, when considering the entire WRF domain, including the three climate regions (Pacific
551 coast, Andes, and Amazon), the GP correction yields a more realistic distribution than the spatial
552 CDF-t, because of the marked polygon borders induced by this second method. However, at
553 local scale in the Andes, the spatial CDF-t method seems to be more similar to the original WRF
554 patterns.

555 In the Andes, the orography is an important factor that influences precipitation. Whereas, the GP
556 model with elevation drift seems to be a good choice for mountainous regions, it was not found to
557 be the best GP model considering our statistical scores. This could be because the majority of our
558 observational data are from the high elevations of the Andes, above 2000 m. This result shows that
559 above this limit, the spatial precipitation pattern is more complex than a simple orographic gradi-
560 ent. Previous studies working with the WRF model in tropical Andes regions have demonstrated
561 the importance of both local mountain winds and synoptic conditions (e.g., Moure et al. 2016;
562 Junquas et al. 2017). In our study, the spatial CDF-t appears to be a bias correction method with a
563 strong capacity for conserving the original spatial precipitation pattern (only considering the An-
564 des above 2000 m). Therefore, depending on the bias characteristics of the WRF simulation, the
565 region of study, and the intended application for the final product, one method or the other should
566 be used for bias correction. If the bias correction is to be applied in a large region including various

567 climate characteristics with strong biases, the GP method would be recommended. Otherwise, if
568 the region is a reduced domain with a relative uniform synoptic climate characteristics but strong
569 influences of local atmospheric processes well represented by the model, the spatial CDF-t method
570 would be preferred.

571 There is still work to be performed on the methods here presented to increase their accuracy.
572 Thus, the perspectives of this study are the following: (i) to deeply analyze the implementation of
573 stationary tests for a GP model, (ii) to develop the spatial CDF-t approach for a more complex spa-
574 tialization strategy, including more than geometrical properties, as is the case for the Voronoï dia-
575 gram. One alternative to the Voronoï diagram could be the use of a functional clustering meethod
576 as in (Antoniadis et al. 2012) where a curve-based clustering is used to reduce the data dimen-
577 sion for constructing a metamodel for West African monsoon. The functional clustering method
578 has the advantage of taking into account time-point correlations of time series spatial data (Anto-
579 niadis et al. 2012). However, available data with longer time series would be necessary to perform
580 such an analysis in the Antisana region. These techniques could be further improved by defining
581 climate subregions with the same climate characteristics. Unfortunately, such a subregion classi-
582 fication would require a longer time-period and a more homogeneous in situ station distribution
583 that what is available now. The spatial CDF-t method could also be tested and improved in other
584 regions of the tropical Andes with a similar spatial climate complexity but with a different tem-
585 poral variability, such as regions of the Peruvian or Bolivian Andes where only one precipitation
586 season occurs during the year. Since the CDF-t method was originally developed for correcting
587 future predictions, this method could be adapted to correct future simulations.

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LIST OF TABLES

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Table 1. Description of meteorological in situ stations. Total precipitation during the 2014-2015 period at each meteorological station and total precipitation in [mm] simulated by WRF at 1 km resolution. Note that for station 12 and 18, we indicate the associated grid-point model used for the bias correction computations. 43

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Table 2. Cross-validation leave-one-out results of annual precipitation for the four Gaussian Process models over the WRF bias proposed with four different drifts. The criteria are calculated for the 2014 and 2015 periods, separately. 44

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866 TABLE 1. Description of meteorological in situ stations. Total precipitation during the 2014-2015 period at
867 each meteorological station and total precipitation in [mm] simulated by WRF at 1 km resolution. Note that for
868 station 12 and 18, we indicate the associated grid-point model used for the bias correction computations.

Number	Elev. [m]	Lon.	Lat.	P. Obs. [mm]	P. WRF [mm]
The Pacific coast					
2	1985	-78.78	-0.21	8656	1568
22	1110	-78.90	-0.21	8954	6892
23	2028	-78.82	-0.25	6132	2140
The Andes					
1	2843	-78.53	-0.39	2447	1475
3	3447	-78.54	-0.20	2510	2478
4	2530	-78.30	-0.10	769	659
5	3317	-78.17	-0.06	835	972
6	2625	-78.42	-0.10	831	932
7	2576	-78.32	-0.16	1221	562
8	3021	-78.42	-0.43	2403	1992
9	3276	-78.63	-0.28	2886	1082
10	3498	-78.52	-0.16	2602	2368
11	2880	-78.51	0.00	995	623
12*	2949	-78.14	0.00	1763	1835
13	2930	-78.89	-0.70	1694	2105
14	3705	-78.43	-0.56	2695	753
15	3157	-78.63	-0.72	1506	757
16	3035	-78.66	-0.83	962	839
17	4009	-78.70	-0.68	1203	1229
18*	2828	-78.23	0.00	1080	1327
20	2487	-78.43	-0.18	1699	948
21	3218	-78.54	-0.09	1824	695
24	3528	-78.66	-0.62	1989	690
26	4812	-78.15	-0.47	2255	2062
The Amazon					
19	2390	-77.93	-0.67	8276	2297
25	1700	-77.82	-0.39	6261	1186

869 TABLE 2. Cross-validation leave-one-out results of annual precipitation for the four Gaussian Process models
870 over the WRF bias proposed with four diferent drifts The criteria are calculated for the 2014 and 2015 periods,
871 separately.

	2014				2015			
	Bias	RMSE	Correlation	Q ₂	Bias	RMSE	Correlation	Q ₂
WRF	1.77	2.89	0.59		2.19	3.67	0.65	
GP+longitude+latitude+alt.	1.71	2.31	0.71	0.44	1.56	2.14	0.80	0.65
GP+longitude+latitude	1.48	2.14	0.76	0.56	1.31	2.08	0.84	0.71
GP+longitude	1.50	2.14	0.76	0.49	1.32	2.11	0.84	0.64
GP+elevation	1.68	2.30	0.72	0.56	1.72	2.29	0.78	0.70

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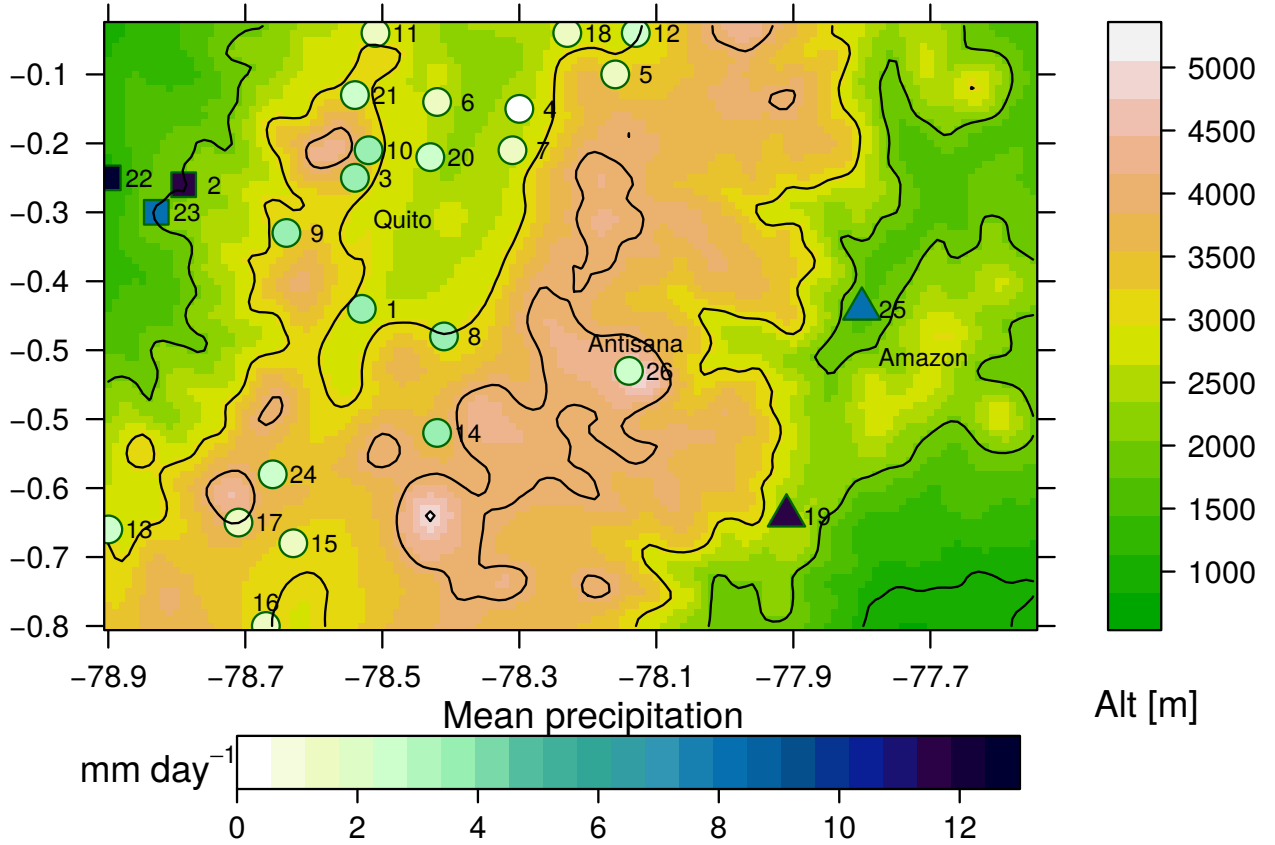


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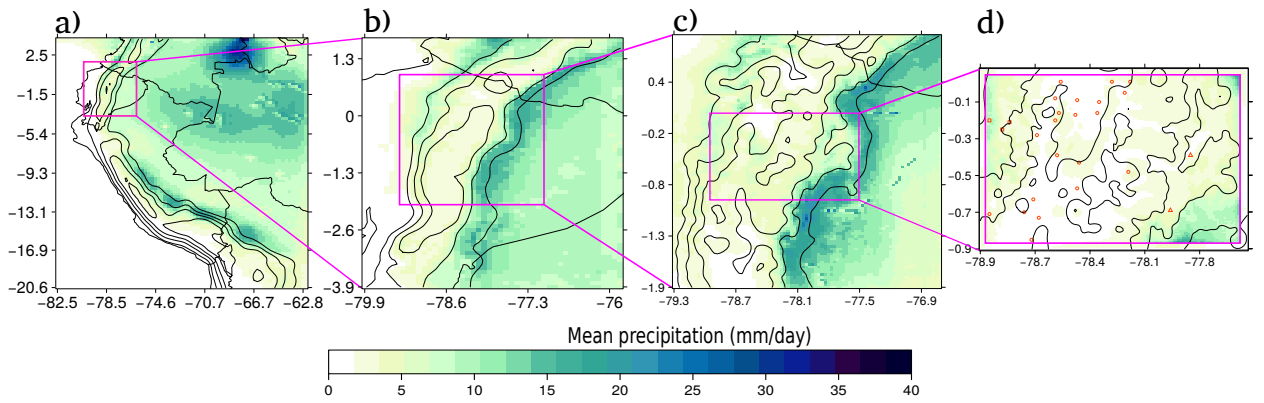


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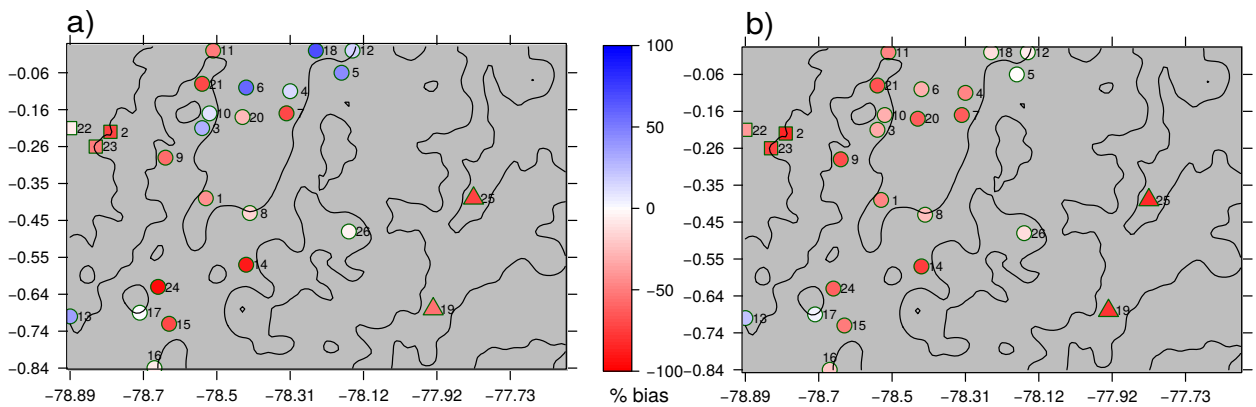
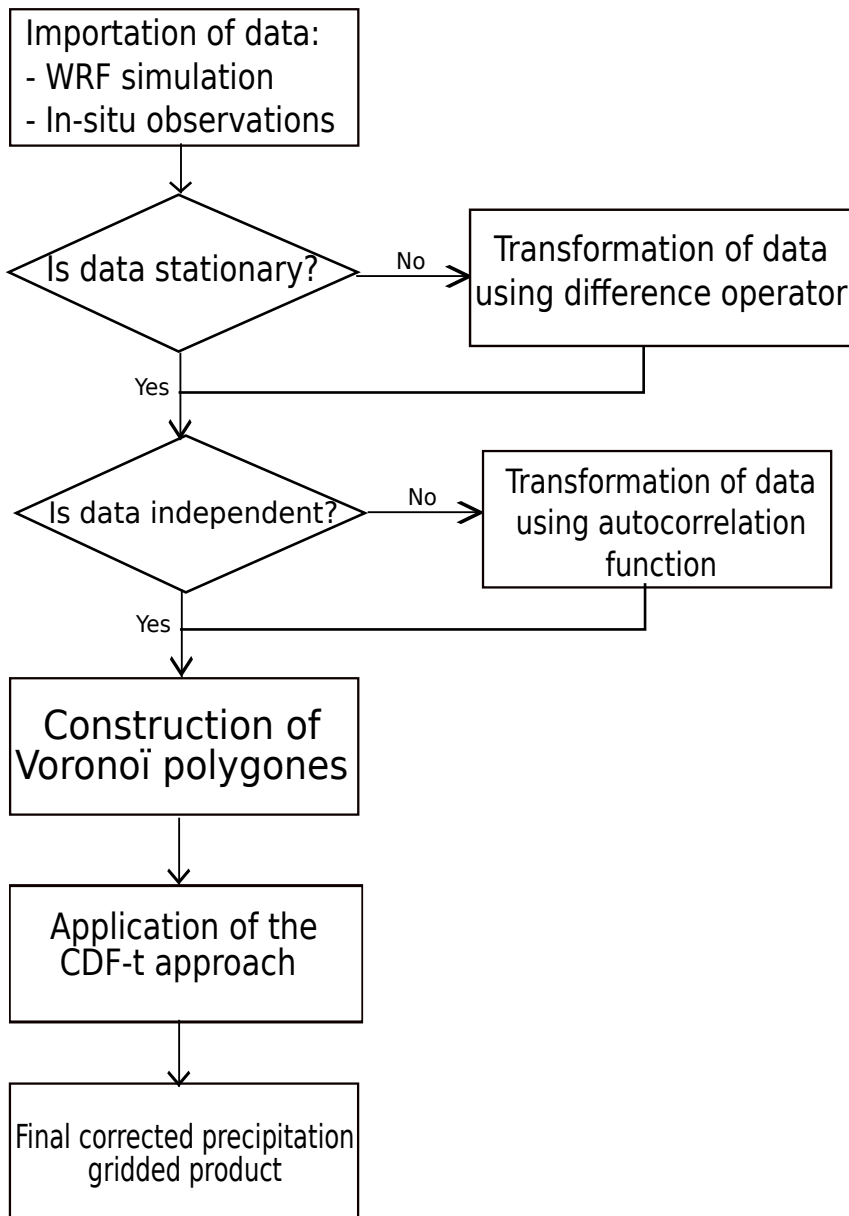


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a)



b)

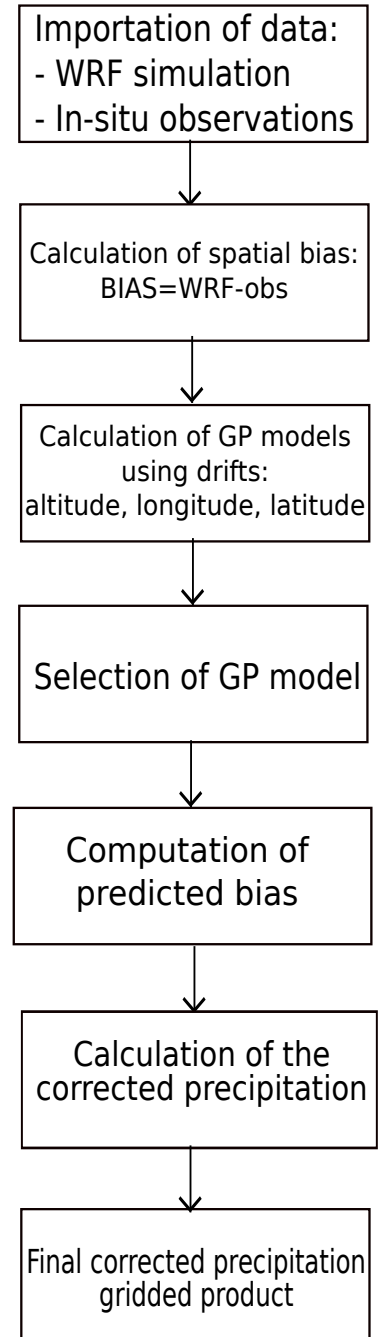


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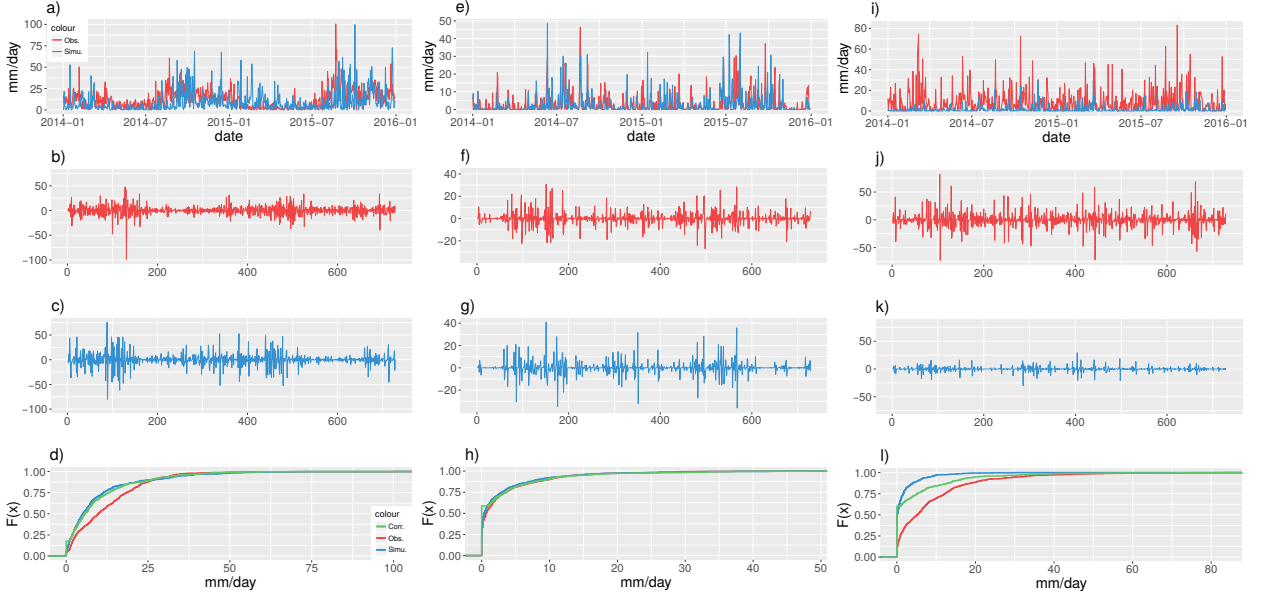


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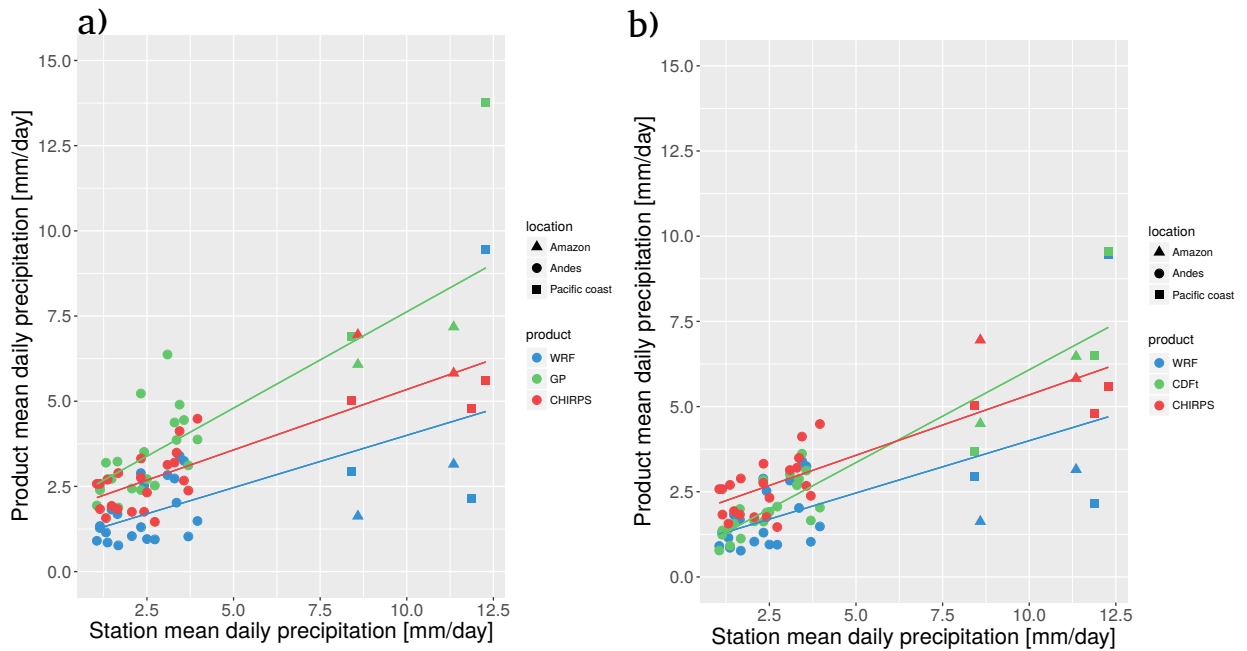


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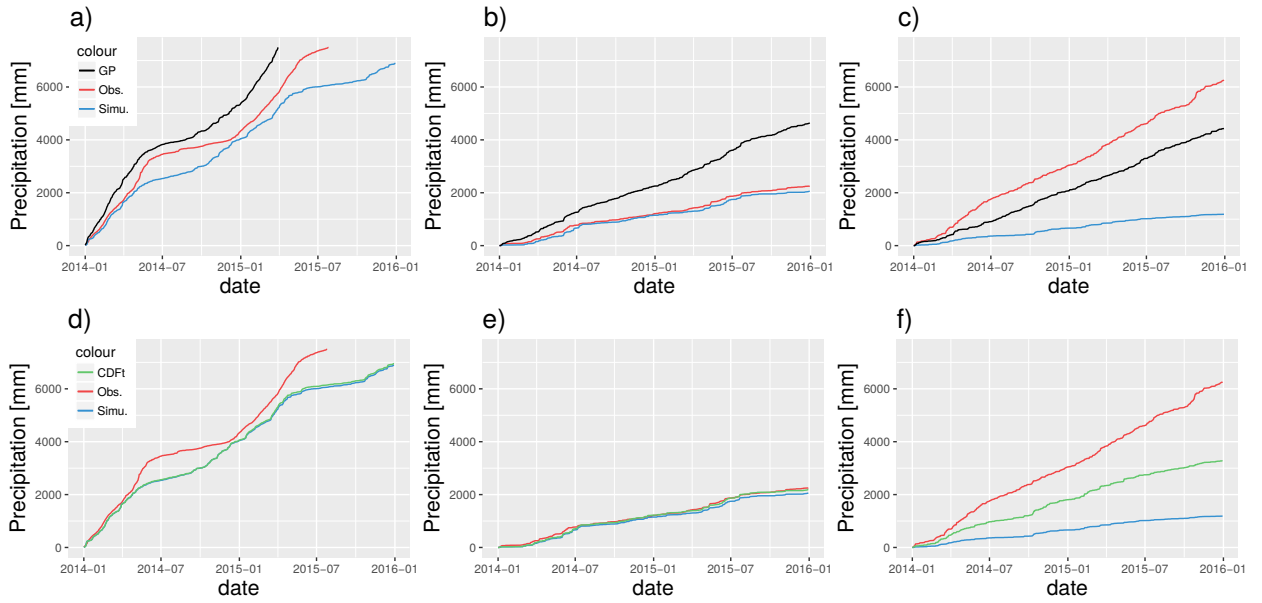


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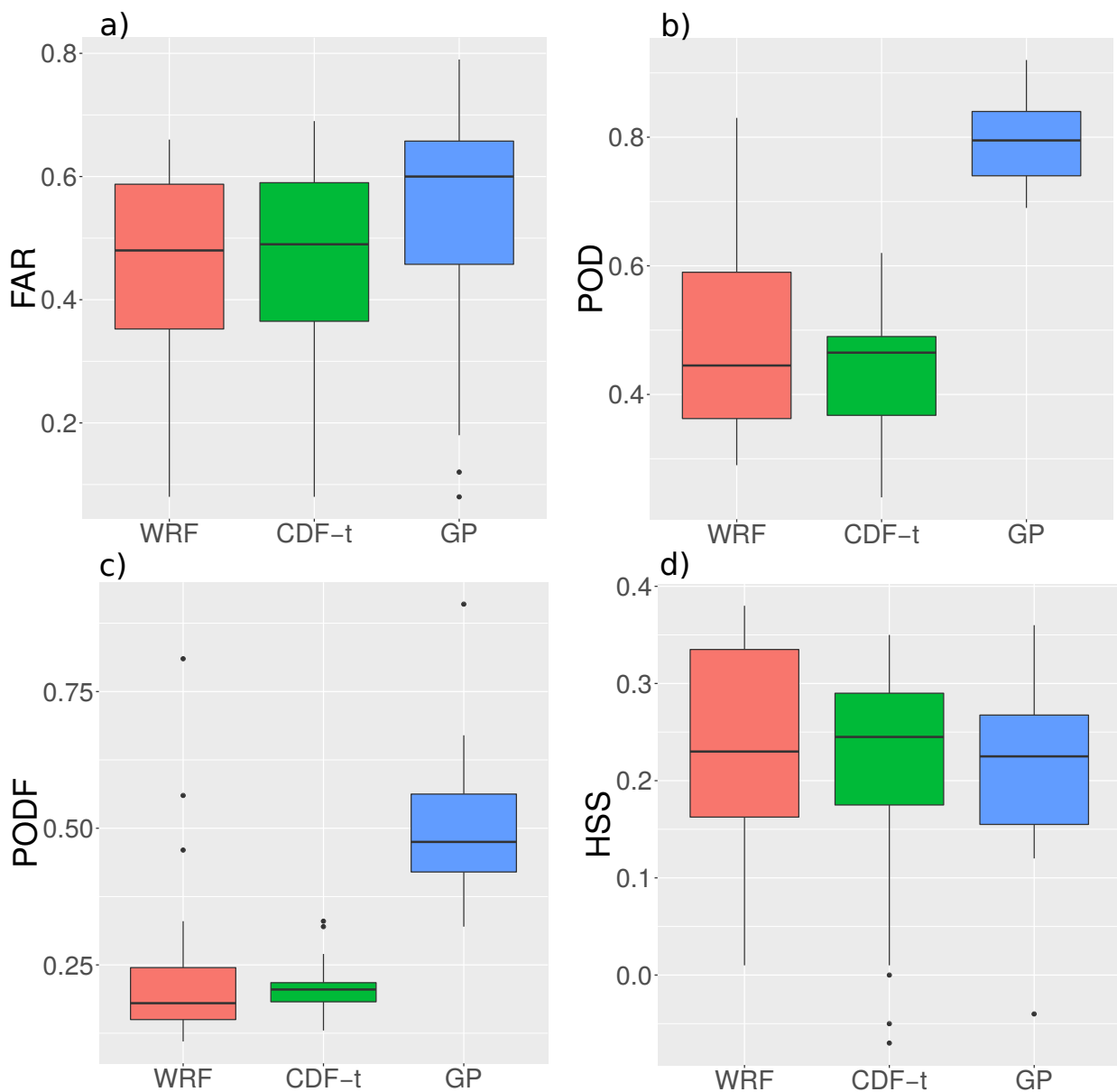


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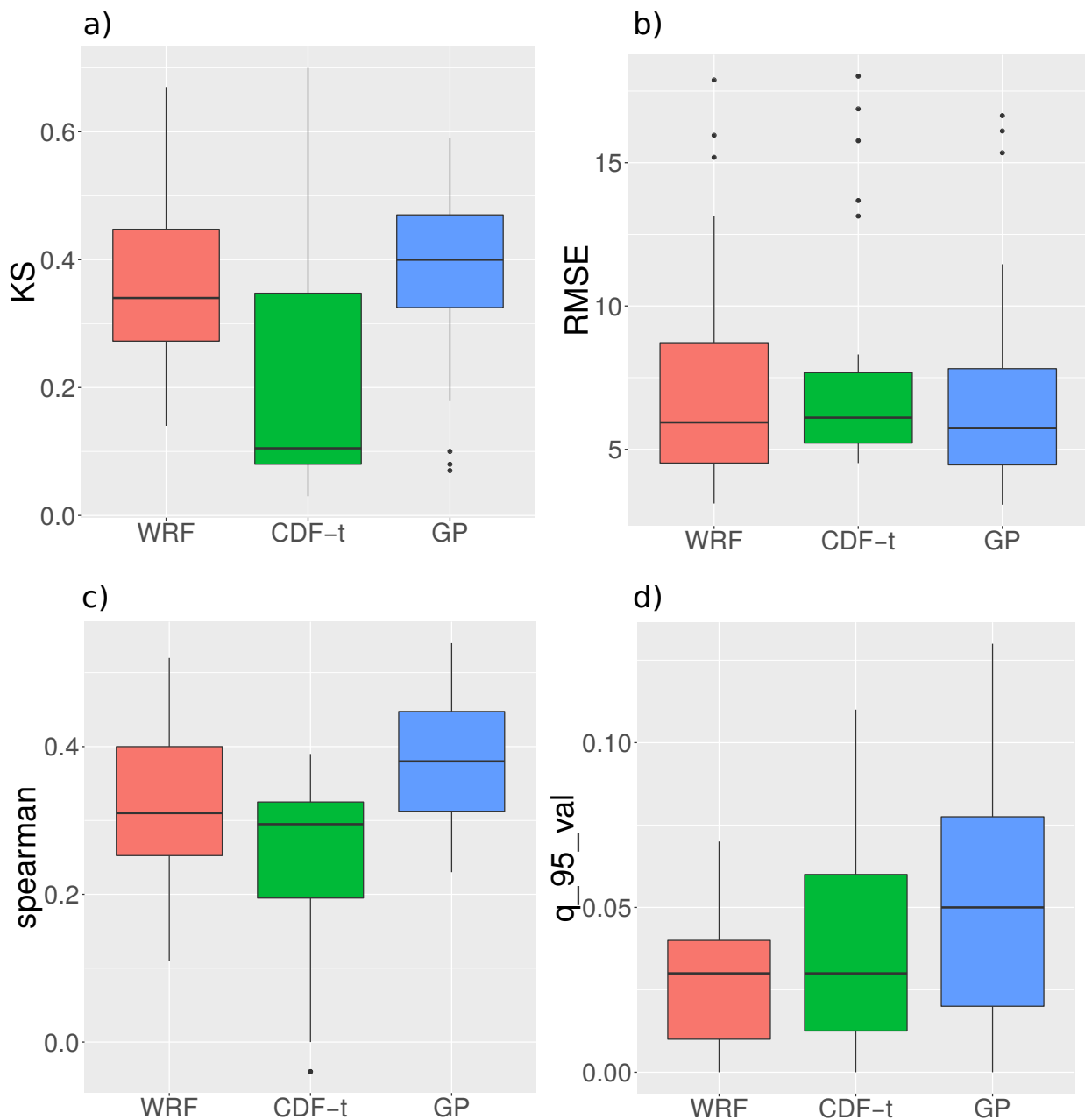


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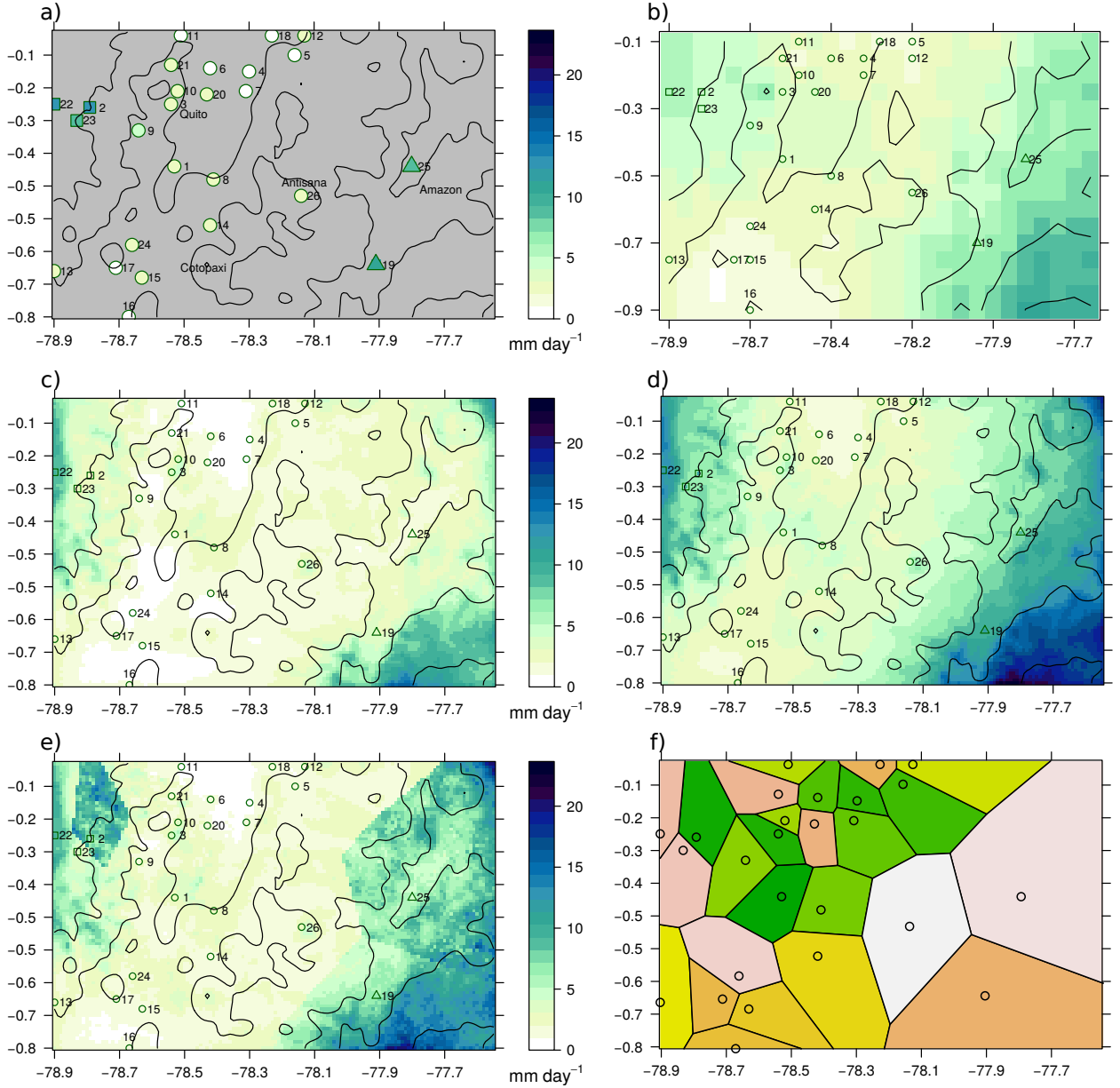


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